

43. **Tichonov estimate with model uncertainty.** (p.91). We wish to choose the slope,  $s$ , of a linear scalar model:

$$y = sx \tag{130}$$

We have a prior estimate of the slope,  $\tilde{s}$ , and we have data,  $(x_i, y_i)$ ,  $i = 1, \dots, M$ . The Tichonov estimate of  $s$  minimizes:

$$T = \lambda(\tilde{s} - s)^2 + (1 - \lambda) \frac{1}{M} \sum_{i=1}^M (y_i - sx_i)^2 \tag{131}$$

where  $0 \leq \lambda \leq 1$ . We will assume that  $x$  and  $y$  are dimensionless quantities.<sup>4</sup>

- (a) Derive an expression for the estimate of  $s$  which minimizes  $T$ .  
 (b) Now consider model uncertainty, with two different info-gap models:

$$\mathcal{U}(h) = \{y = sx + u : |u| \leq h\}, \quad h \geq 0 \tag{132}$$

$$\mathcal{U}(h) = \{y = sx + ux^2 : |u| \leq h\}, \quad h \geq 0 \tag{133}$$

For each info-gap model, derive an expression for the robustness of an estimate of the slope. How does the robust-satisficing estimate differ between the two models? How do they differ from the Tichonov estimate? Note that, because  $x$  and  $y$  are dimensionless, the horizons of uncertainty in these two info-gap models are also dimensionless. This makes the robustnesses which are evaluated with these two info-gap models comparable.<sup>5</sup>

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<sup>4</sup> If  $x$  and  $y$  have units, and even if they have the same units, then the units of  $T$  in eq.(131) are undefined. This means that the relative weights of the two terms in  $T$  are controlled by the units, not by the value of  $\lambda$ .

<sup>5</sup>If  $x$  and  $y$  have units then it is necessary to calibrate the two robustnesses, which requires judgment and cannot be done uniquely. However, if  $x$  and  $y$  have units then we also face a different problem, noted in footnote 4.

**Solution for problem 43.** (p.25)

(a) We find the Tichonov optimal slope by differentiation:

$$\frac{\partial T(s)}{\partial s} = -2\lambda(\tilde{s} - s) - \frac{2(1-\lambda)}{M} \sum_{i=1}^M (y_i - sx_i)x_i \quad (756)$$

$$= \left( 2\lambda + \frac{2(1-\lambda)}{M} x^T x \right) s - 2\lambda\tilde{s} - \frac{2(1-\lambda)}{M} x^T y \quad (757)$$

The 2nd derivative is positive so the solution is a minimum. Thus the Tichonov optimal slope is obtained by equating eq.(757) to zero:

$$s_T = \frac{\lambda\tilde{s} + [(1-\lambda)/M]x^T y}{\lambda + [(1-\lambda)/M]x^T x} \quad (758)$$

We see that, if  $\lambda = 1$  then  $s_T = \tilde{s}$ . Likewise, if  $\lambda = 0$  then  $s_T$  equals the ordinary least-squares optimal slope.

(b) Let  $T(s, u)$  denote the Tichonov error with model uncertainty. The robustness of slope  $s$ , with requirement of error no greater than  $T_c$ , is defined as:

$$\hat{h}(s, T_c) = \max \left\{ h : \left( \max_{u \in \mathcal{U}(h)} T(s, u) \right) \leq T_c \right\} \quad (759)$$

Let  $\mu(h)$  denote the inner maximum. We now consider the two different info-gap models.

*Info-gap model of eq.(132), p.25.* The Tichonov error is:

$$T(s, u) = \lambda(\tilde{s} - s)^2 + \frac{1-\lambda}{M} \sum_{i=1}^M (y_i - sx_i - u)^2 \quad (760)$$

$$= \underbrace{\lambda(\tilde{s} - s)^2 + \frac{1-\lambda}{M} \sum_{i=1}^M (y_i - sx_i)^2}_{T_o(s)} - 2u \frac{1-\lambda}{M} \sum_{i=1}^M (y_i - sx_i) + (1-\lambda)u^2 \quad (761)$$

where  $T_o(s)$  is the ordinary Tichonov error.

We find  $\mu(h)$  at  $u = -h \operatorname{sgn} \left( \sum_{i=1}^M (y_i - sx_i) \right)$ . Thus:

$$\mu(h) = T_o(s) + 2h \frac{1-\lambda}{M} \left| \sum_{i=1}^M (y_i - sx_i) \right| + (1-\lambda)h^2 \quad (762)$$

$$= T_o(s) + 2h(1-\lambda) |\bar{y} - s\bar{x}| + (1-\lambda)h^2 \quad (763)$$

This is the inverse of the robustness curve: a plot of  $h$  vs.  $\mu(h)$  is the same as a plot of  $\hat{h}(s, T_c)$  vs.  $T_c$ .

Consider two different slope values, one of them the Tichonov optimum  $s_T$ . Let  $\mu(h, s)$  and  $\mu(h, s_T)$  denote the inverse robustnesses, eq.(763). Equating  $\mu(h, s) = \mu(h, s_T)$  we see that their robustness curves cross at the following value of robustness if it is positive:

$$h_\times = \frac{T_o(s) - T_o(s_T)}{2(1-\lambda)(|\bar{y} - s_T\bar{x}| - |\bar{y} - s\bar{x}|)} \quad (764)$$

By definition,  $T_o(s_T) \leq T_o(s)$ , so the numerator is non-negative. If  $\lambda < 1$  and  $s_T \neq \bar{y}/\bar{x}$ , then one can choose  $s$  in infinitely ways so that the denominator is also positive. In other words, given these two conditions, we have proven that there are an infinite number of non-Tichonov slopes which are more robust than  $s_T$  for all values of  $T_c$  exceeding a threshold.

*Info-gap model of eq.(133), p.25.* The Tichonov error is:

$$T(s, u) = \lambda(\tilde{s} - s)^2 + \frac{1 - \lambda}{M} \sum_{i=1}^M (y_i - sx_i - ux_i^2)^2 \quad (765)$$

$$= \underbrace{\lambda(\tilde{s} - s)^2 + \frac{1 - \lambda}{M} \sum_{i=1}^M (y_i - sx_i)^2}_{T_o(s)} - 2u \frac{1 - \lambda}{M} \sum_{i=1}^M (y_i - sx_i)x_i^2 + u^2 \frac{1 - \lambda}{M} \sum_{i=1}^M x_i^4 \quad (766)$$

where  $T_o(s)$  is the ordinary Tichonov error as before.

We find  $\mu(h)$  at  $u = -h \operatorname{sgn} \left( \sum_{i=1}^M (y_i - sx_i)x_i^2 \right)$ . Thus:

$$\mu(h) = T_o(s) + 2h \frac{1 - \lambda}{M} \left| \sum_{i=1}^M (y_i - sx_i)x_i^2 \right| + h^2 \frac{1 - \lambda}{M} \sum_{i=1}^M x_i^4 \quad (767)$$

$$= T_o(s) + 2h(1 - \lambda) \left| \overline{yx^2} - \overline{sx^3} \right| + h^2(1 - \lambda) \overline{x^4} \quad (768)$$

This is the inverse of the robustness curve: a plot of  $h$  vs.  $\mu(h)$  is the same as a plot of  $\hat{h}(s, T_c)$  vs.  $T_c$ .

We can again argue, like in eq.(764), that there are an infinity of non-Tichonov slopes which are more robust than  $s_T$ . Evaluating eq.(768) for  $s$  and for  $s_T$  and solving for  $h$  we find that the robustness curves cross at:

$$h_\times = \frac{T_o(s) - T_o(s_T)}{2(1 - \lambda) \left( \left| \overline{yx^2} - \overline{s_T x^3} \right| - \left| \overline{yx^2} - \overline{sx^3} \right| \right)} \quad (769)$$

This is positive if  $\lambda < 1$  and  $s_T \neq \overline{yx^2}/\overline{x^3}$ .

*Comparing the robustnesses of the two info-gap models.* The robustnesses are directly commensurable because they are both dimensionless. We ask: is one model more robust than the other, or do their robustness curves cross one another?

Let us denote the inverse robustnesses for these two info-gap models, eqs.(763) and (768), by  $\mu_1(h)$  and  $\mu_2(h)$  respectively.

Note that:

$$\mu_1(0) = T_o(s) = \mu_2(0) \quad (770)$$

This means that the robustness curves sprout off of the  $T_c$  axis at the same value,  $T_o(s)$ .

Do the robustness curves cross again at positive robustness, or is one robust-dominant?

Equate  $\mu_1(h) = \mu_2(h)$  and solve for  $h$ . The robustness curves cross at positive robustness if and only if there is a positive solution:

$$h_\times = \frac{2 \left( \left| \overline{y} - \overline{s\bar{x}} \right| - \left| \overline{yx^2} - \overline{sx^3} \right| \right)}{\overline{x^4} - 1} \quad (771)$$

This may positive.